

| Ref # | Hits | Search Query  | DBs   | Default Operator | Plurals | Time Stamp       |
|-------|------|---|---|------------------|---------|------------------|
| S1    | 570  | 717/124.ccls.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 15:03 |
| S2    | 122  | 717/124.ccls. and (vision or image)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 15:04 |
| S3    | 70   | 717/105.ccls. and (vision or image)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 15:04 |
| S4    | 74   | 717/120.ccls. and (vision or image)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 15:04 |
| S5    | 65   | 717/171.ccls. and (vision or image)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 15:24 |
| S6    | 6455 | "machine vision" or "robot vision" or "vision processing" and (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 )   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 15:27 |
| S7    | 6416 | "machine vision" or "robot vision" or "vision processing" and (process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) and (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and (tool or parameter) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/08/16 16:18 |

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| S8  | 1397 | ("machine vision" or "robot vision" or "vision processing" ) and (process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) and (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and (tool or parameter)  | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | OFF | 2005/08/16 15:36 |
| S9  | 52   | ("machine vision" or "robot vision" or "vision processing" )same (process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and tool and parameter  | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | OFF | 2005/08/16 15:36 |
| S10 | 52   | ("machine vision" or "robot vision" or "vision processing" ) same (process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and tool and parameter | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | OFF | 2005/08/16 15:37 |
| S11 | 13   | ("5265014"   "5577165"   "5701400"   "5748974"   "5777614"   "5781179"   "5884294"   "5963911"   "6021403"   "6209788"   "6345111"   "6438523"   "6578005").PN. OR ("6779060").URPN.  | US-PGPUB; USPAT; USOCR                      | OR | OFF | 2005/08/16 16:18 |
| S12 | 2812 | ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor ) and (distributed or network\$3 or corba or client or server )  | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | OFF | 2005/08/16 16:22 |

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| S13 | 225  | ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 ) near3 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor ) same (distributed or network\$3 or corba or client or server ) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | OFF | 2005/08/16 16:22 |
| S14 | 20   | ("4511886"   "4943855"   "5103306"   "5111288"   "5144450"   "5202759"   "5218627"   "5227877"   "5236199"   "5430480"   "5444476"   "5509009"   "5510834"   "5521634"   "5548346"   "5598209"   "5619183"   "5625410"   "5652619"   "5793367").PN.                     | US-PGPUB; USPAT; USOCR                      | OR | OFF | 2005/08/16 16:45 |
| S15 | 22   | ("5926209").URPN.   | USPAT                                       | OR | OFF | 2005/08/16 16:51 |
| S16 | 372  | (choic or choos\$3 or select\$3 ) near2 (vision or camera or optical) near2 (software or application or module or tool or component)  | USPAT                                       | OR | OFF | 2005/08/16 16:52 |
| S17 | 374  | (choice or choos\$3 or select\$3 ) near2 (vision or camera or optical) near2 (software or application or module or tool or component)   | USPAT                                       | OR | OFF | 2005/08/16 16:58 |
| S18 | 16   | (user or customer or purchaser or kiosk ) near3 (format\$4 or manipul\$3 or choice or choos\$3 or select\$3 ) near2 (vision or camera or optical) near2 (software or application or module or tool or component)  | USPAT                                       | OR | ON  | 2005/08/16 16:59 |
| S19 | 12   | ("5940296"   "5956419"   "5963212"   "5999213"   "6088731"   "6125385"   "6161126"   "6256773"   "6278433"   "6298474"   "6380949"   "6522906").PN. OR ("6931602").URPN.  | US-PGPUB; USPAT; USOCR                      | OR | OFF | 2005/08/16 17:14 |
| S20 | 1724 | (camera or vision or image) adj simulat\$3  | US-PGPUB; USPAT; USOCR                      | OR | OFF | 2005/08/16 17:15 |
| S21 | 22   | ((optical or camera or vision) adj simulat\$3 ) same parameter  | US-PGPUB; USPAT; USOCR                      | OR | OFF | 2005/08/16 17:15 |
| S22 | 4    | ((optical or camera or vision) adj simulat\$3 ) same parameter same (network\$3 or server or client or corba or distributed wan or lan or internet )  | US-PGPUB; USPAT; USOCR                      | OR | OFF | 2005/08/16 17:17 |

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| S23 | 2    | (( camera or vision) adj simulat\$3 ) same parameter and (network\$3 or server or client or corba or distributed wan or lan or internet )   | US-PGPUB; USPAT; USOCR | OR | OFF | 2005/08/16 17:23 |
| S24 | 1    | "6931602".pn.   | US-PGPUB; USPAT; USOCR | OR | OFF | 2005/08/17 07:18 |
| S25 | 520  | consumer near3 (choice or choos\$3 or indicat\$3 or select\$3 ) same (imag\$3 or camera or photo or vision ) and (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet )                         | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 07:22 |
| S26 | 195  | consumer near3 (choice or choos\$3 or indicat\$3 or select\$3 ) same (imag\$3 or camera or photo or vision ) same (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet )                        | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 07:22 |
| S27 | 53   | consumer near3 (choice or choos\$3 or indicat\$3 or select\$3 ) near5 (imag\$3 or camera or photo or vision ) same (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet )                       | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 07:51 |
| S28 | 1233 | (consumer or user) near3 (choice or choos\$3 or indicat\$3 or select\$3 ) near5 (imag\$3 or camera or photo or vision ) same (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet ) and shar\$3 | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 09:14 |
| S29 | 24   | silver.in. and cognex.as.   | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 09:27 |
| S30 | 0    | visioneer.as. and blair.in.   | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 09:28 |
| S31 | 3794 | blair.in.   | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 09:28 |
| S32 | 306  | blair.in. and image   | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 09:29 |
| S33 | 2    | blair.in. and "image management"  | US-PGPUB; USPAT; USOCR | OR | ON  | 2005/08/17 15:23 |

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|-----|------|--|---|----|-----|------------------|
| S34 | 0    | "6931602".pn. and corba  | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | ON  | 2005/08/17 15:25 |
| S35 | 0    | (( "6493677" "6298474"<br>"54817126798531").pn. or<br>"20030055745" or<br>"20040100465") and corba | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | ON  | 2005/08/17 15:27 |
| S36 | 240  | ("machine vision" or "image<br>processing" or "vision processing"<br>) and corba                   | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | ON  | 2005/08/17 15:28 |
| S37 | 1    | ("machine vision" or "image<br>processing" or "vision processing"<br>) same corba                  | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | ON  | 2005/08/17 15:28 |
| S38 | 445  | 715/733.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:13 |
| S39 | 11   | 715/733.ccls. and vision   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:18 |
| S40 | 237  | 715/771.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:18 |
| S41 | 25   | 715/771.ccls. and vision   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:20 |
| S42 | 3380 | 709/217.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:20 |
| S43 | 79   | 709/217.ccls. and vision   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:20 |
| S44 | 844  | 719/315.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:21 |

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| S45 | 18    | 719/315.ccls. and vision   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:21 |
| S46 | 2     | 719/319.ccls. and vision   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:22 |
| S47 | 7     | 345/520.ccls. and vision   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:22 |
| S48 | 305   | 345/520.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:22 |
| S49 | 305   | 345/520.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:22 |
| S50 | 106   | 719/319.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/08/18 08:22 |
| S51 | 11830 | ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor ) and (distributed or network\$3 or corba or client or server )  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2006/02/07 15:45 |
| S52 | 5473  | ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) and (remot\$3 or distributed or network\$3 or corba or client or server ) and select\$3 and (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/07 16:08 |

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| S53 | 2538 | ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) same (remot\$3 or distributed or network\$3 or corba or client or server ) and select\$3 and (client or customer ) near3 (information or account or data or records or password or id or identi\$6 )   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/07 16:08 |
| S54 | 1453 | ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) same (remot\$3 or distributed or network\$3 or corba or client or server ) and select\$3 and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) )   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/07 16:09 |
| S55 | 943  | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) same (remot\$3 or distributed or network\$3 or corba or client or server ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 select\$3 and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) ) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 09:44 |



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| S56 | 1423 | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 (remot\$3 or distributed or network\$3 or corba or client or server ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 select\$3 and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) )   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/07 16:12 |
| S57 | 154  | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 (remot\$3 or distributed or network\$3 or corba or client or server ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 select\$3 and (verify or verification or ensur\$3 or certify or certification or validat\$3) same ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) ) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/07 16:28 |
| S58 | 2    | "6931602".pn.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/07 16:31 |



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|-----|------|---|---|----|-----|------------------|
| S59 | 3    | "6608628".pn.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/07 16:31 |
| S60 | 12   | ("5940296"   "5956419"  <br>"5963212"   "5999213"  <br>"6088731"   "6125385"  <br>"6161126"   "6256773"  <br>"6278433"   "6298474"  <br>"6380949"   "6522906").PN. OR<br>("6931602").URPN.  | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | OFF | 2006/02/07 16:40 |
| S61 | 6    | remot\$3 near3 surgery same<br>vision   | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | OFF | 2006/02/07 16:42 |
| S62 | 47   | remot\$3 near3 surgery same<br>camera   | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | OFF | 2006/02/07 16:42 |
| S63 | 13   | ("6298474").URPN.   | USPAT   | OR | OFF | 2006/02/07 16:51 |
| S64 | 6797 | ("machine vision" or "robot vision"<br>or vision or optical or camera or<br>imag\$3 or sensor ) and ( select\$3<br>near5 tool ) and ( verify or<br>verification or ensur\$3 or certify or<br>certification or validat\$3)                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/08 09:48 |
| S65 | 123  | ("machine vision" or "robot vision"<br>or vision or optical or camera or<br>imag\$3 or sensor ) same (<br>select\$3 near5 tool ) same ( verify<br>or verification or ensur\$3 or certify<br>or certification or validat\$3)                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/08 10:09 |
| S66 | 4873 | ("machine vision" or "robot vision"<br>or vision or optical or camera or<br>imag\$3 or sensor ) same (<br>select\$3 near5 (tool or feature ) )<br>and ( verify or verification or<br>ensur\$3 or certify or certification<br>or validat\$3) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/08 10:11 |
| S67 | 1342 | ("machine vision" or "robot vision"<br>or vision or optical or camera or<br>imag\$3 or sensor ) same (<br>select\$3 near5 (tool ) ) and ( verify<br>or verification or ensur\$3 or certify<br>or certification or validat\$3)               | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/08 10:11 |
| S68 | 517  | ("machine vision" or "robot vision"<br>or vision or optical or camera or<br>imag\$3 or sensor ) near5 (<br>select\$3 near5 (tool ) ) and ( verify<br>or verification or ensur\$3 or certify<br>or certification or validat\$3)              | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2006/02/08 10:11 |

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| S69 | 400     | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3)  | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2006/02/08 10:12 |
| S70 | 7214166 | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) or (client or customer or user ) or (information or account or data or records or password or id or identi\$6 )      | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2006/02/08 10:14 |
| S71 | 398     | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and ( parameter or factor or type or number or value ) or (client or customer or user ) or (information or account or data or records or password or id or identi\$6 ) )   | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2006/02/08 10:15 |
| S72 | 391     | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) and ( (client or customer or user ) or (information or account or data or records or password or id or identi\$6 ) ) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2006/02/08 10:15 |
| S73 | 338     | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) and (client or customer or user ) and (information or account or data or records or password or id or identi\$6 )    | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2006/02/08 10:16 |

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| S74 | 291  | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) and (client or customer or user ) same (information or account or data or records or password or id or identi\$6 )                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 12:14 |
| S75 | 272  | S74 not S65   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 10:16 |
| S76 | 3    | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 ( (client or customer or user ) near3 input) and (information or account or data or records or password or id or identi\$6 ) and (parameter or factor or type or number or value ) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 13:39 |
| S77 | 746  | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( (tool ) ) same (verify or verification or ensur\$3 or certify or certification or validat\$3)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 13:41 |
| S78 | 16   | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) same (verify or verification or ensur\$3 or certify or certification or validat\$3)  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 13:51 |
| S79 | 1717 | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 13:52 |

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|-----|-----|---|---|----|----|------------------|
| S80 | 62  | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) same (verify or verification or ensur\$3 or certify or certification or validat\$3)  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 13:59 |
| S81 | 46  | S80 not S78   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 13:52 |
| S82 | 269 | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 (user or client or customer or employee)  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 14:01 |
| S83 | 269 | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 (user or client or customer or employee) and (verify or verification or ensur\$3 or certify or certification or validat\$3)                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 14:01 |
| S84 | 269 | ("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor or computervision ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 (user or client or customer or employee) and (verify or verification or ensur\$3 or certify or certification or validat\$3) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 14:02 |

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| S85 | 259 | S84 not S80 not S78 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2006/02/08 14:02 |
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